

MATH 2700: TEST 01 (100 points.)

NAME: \_\_\_\_\_

DIRECTIONS: Show all work.

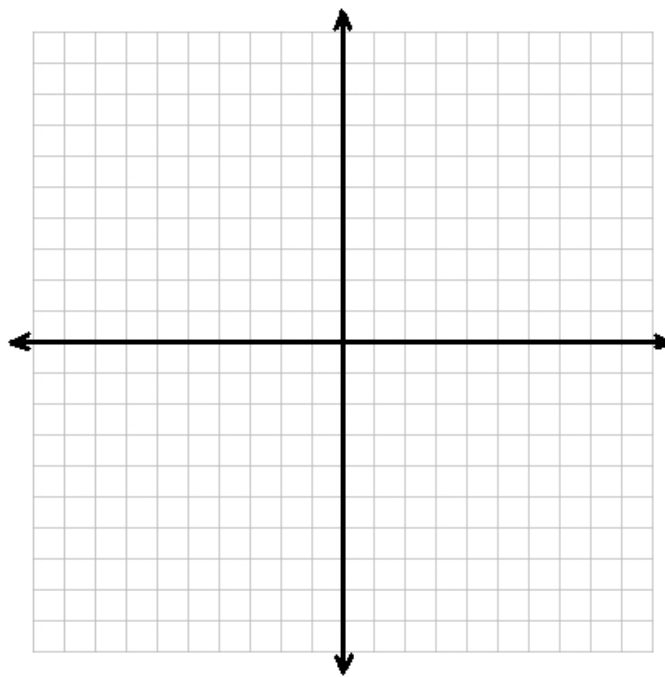
1. (a) A vector,  $\vec{v}$  is a mathematical object defined by two quantities:
  - i. its \_\_\_\_\_, denoted by  $\|\vec{v}\|$ , and ...
  - ii. its \_\_\_\_\_, denoted by  $\hat{v}$ .
- (b) A quick way to check if two nonzero vectors  $\vec{v}$  and  $\vec{w}$  are orthogonal is to show \_\_\_\_\_.
- (c) To construct a vector orthogonal to two nonzero vectors  $\vec{v}$  and  $\vec{w}$ , we can compute \_\_\_\_\_.
- (d) Find a vector **parallel** to the line  $\vec{L} = \langle 2 - 3t, 6 + t, 5 \rangle$ .
- (e) Find a vector **normal** to the plane:  $3x + 2y + z = 6$ .
- (f) Show the intersection of the cone  $z^2 = x^2 + y^2$  and the plane  $z = y + 1$  is a parabola.

2. An object in the  $xy$ -plane positioned at the origin is being acted upon by two forces. One force,  $\vec{F}_1$  has a magnitude of 8 N and acts at an angle of  $60^\circ$  with respect to the positive  $x$ -axis. The second force,  $\vec{F}_2$  is pulling directly left with a force of 4 N.

(a) Find the component forms of  $\vec{F}_1$  and  $\vec{F}_2$ .

(b) Find the magnitude and direction of the force required to keep the object from moving,  $\vec{v}$ .  
Explain your reasoning.

(c) Sketch  $\vec{F}_1$ ,  $\vec{F}_2$ , and  $\vec{v}$  on the axes below and check your answer graphically.



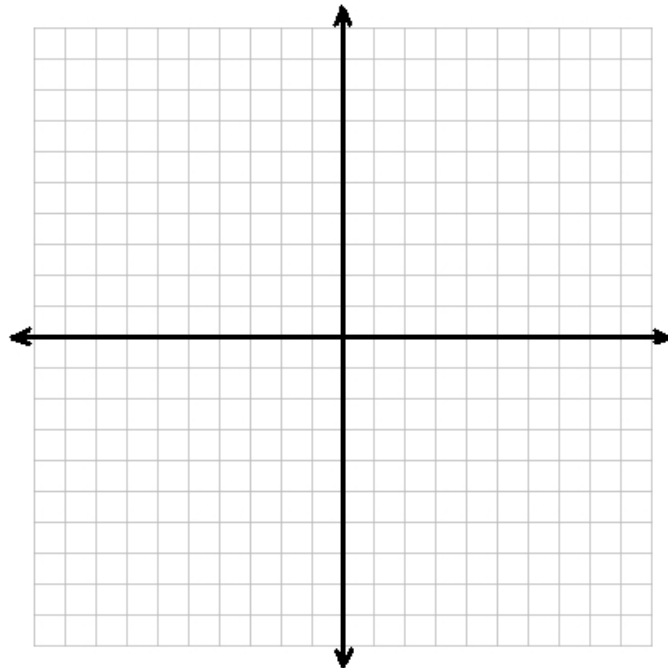
3. Let  $\vec{v} = \langle -5, 10 \rangle$  and  $\vec{w} = \langle 4, -3 \rangle$ .

(a) Find and simplify  $\vec{p} = \text{proj}_{\vec{w}} \vec{v}$

(b) Find  $\vec{q} = \vec{v} - \vec{p}$ , and use the dot product to show  $\vec{q} \perp \vec{w}$ .

(c) On the axes below:

- Graph  $\vec{v}$ ,  $\vec{w}$ , and  $\vec{p}$  in standard position.
- Graph  $\vec{q}$  so that the initial point of  $\vec{q}$  is the terminal point of  $\vec{p}$ .
- Geometrically verify that  $\vec{v} = \vec{p} + \vec{q}$ .



4. Let  $P(0, -2, 4)$  and  $Q(-2, 1, 10)$ .

(a) Find  $\overrightarrow{PQ}$ ,  $\|\overrightarrow{PQ}\|$ , and  $\widehat{PQ}$ .

(b) Find the equation of the sphere which contains  $P$  and  $Q$  as antipodal points.

(c) Find the vector form of the line containing the origin which is parallel to  $\overrightarrow{PQ}$ .

(d) Let  $R(2, 0, 4)$ . Find  $\overrightarrow{PR}$  and  $\overrightarrow{PQ} \times \overrightarrow{PR}$ .

(e) Find the equation of the plane containing  $P$ ,  $Q$ , and  $R$ .

Write your answer in the form:  $Ax + By + Cz = D$  where  $A > 0$ .

(f) Find the distance from the origin to the plane containing  $P$ ,  $Q$ , and  $R$ .

5. Consider the equation  $S : x + y + 2z = 4$ .

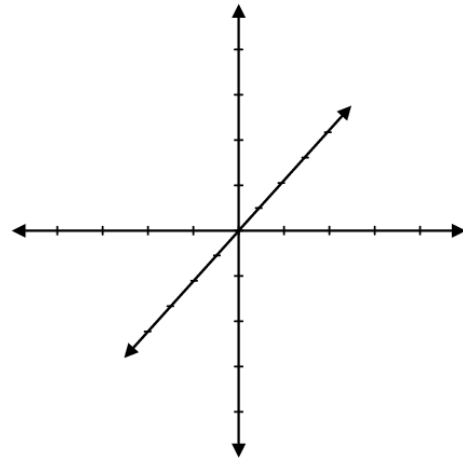
(a) How do you know the graph of  $S$  is a plane?

(b) Find the equations for each of the traces and graph  $S$  in the first octant. (Label the axis intercepts.)

- $xy$  - trace:

- $xz$  - trace:

- $yz$  - trace:



**BONUS:** (+5) Find the point on the graph of  $S$  which is closest to the origin.

6. Let  $\vec{v} = \langle v_1, v_2, v_3 \rangle$  and  $\vec{w} = \langle w_1, w_2, w_3 \rangle$  be two nonzero vectors. Prove  $\vec{v}$  is orthogonal to  $\vec{v} \times \vec{w}$ .

**HINT:** Feel free to use the properties of the triple scalar product . . .

7. Explain which properties of the dot product are being used to prove the claim below:

**CLAIM:** If  $\vec{v}$  and  $\vec{w}$  are nonzero vectors, and  $\vec{p} = \text{proj}_{\vec{w}} \vec{v}$ , then  $\vec{q} = \vec{v} - \vec{p}$  is orthogonal to  $\vec{w}$ .

**PROOF:** We show  $\vec{w} \cdot \vec{q} = 0$ :

$$\begin{aligned}
 \vec{w} \cdot \vec{q} &= \vec{w} \cdot (\vec{v} - \vec{p}) & \text{REASON: } \vec{q} = \vec{v} - \vec{p} \\
 &= \vec{w} \cdot \vec{v} - \vec{w} \cdot \vec{p} & \text{REASON: } \underline{\hspace{2cm}} \\
 &= \vec{w} \cdot \vec{v} - \vec{w} \cdot \left( \frac{\vec{v} \cdot \vec{w}}{\vec{w} \cdot \vec{w}} \vec{w} \right) & \text{REASON: definition of } \vec{p} = \text{proj}_{\vec{w}} \vec{v} \\
 &= \vec{w} \cdot \vec{v} - \left( \frac{\vec{v} \cdot \vec{w}}{\vec{w} \cdot \vec{w}} \right) (\vec{w} \cdot \vec{w}) & \text{REASON: } \underline{\hspace{2cm}} \\
 &= \vec{w} \cdot \vec{v} - \frac{\vec{v} \cdot \vec{w}}{\cancel{\vec{w} \cdot \vec{w}}} \cancel{\vec{w} \cdot \vec{w}} \\
 &= \vec{w} \cdot \vec{v} - \vec{v} \cdot \vec{w} & \text{REASON: } \underline{\hspace{2cm}} \\
 &= 0 & \checkmark
 \end{aligned}$$

8. Suppose  $\hat{v}$  and  $\hat{w}$  are **orthogonal** and  $\vec{u} = a\hat{v} + b\hat{w}$ .

(a) Explain why  $\|a\hat{v}\| = |a|$  and  $\|b\hat{w}\| = |b|$ .

(b) Sketch a vector diagram relating  $\vec{u}$ ,  $\hat{v}$ , and  $\hat{w}$ .

(c) Turn your vector diagram in part (a) into a triangle and explain why  $\|\vec{u}\|^2 = a^2 + b^2$ .

What famous theorem is this?



**BONUS:** Fill in the reasoning below to prove the claim made in 8c using properties of the dot product:

**CLAIM:**  $\|\vec{u}\|^2 = a^2 + b^2$ .

**PROOF:**

$$\|\vec{u}\|^2 = \vec{u} \cdot \vec{u}$$

$$= (a\hat{v} + b\hat{w}) \cdot (a\hat{v} + b\hat{w}) \quad \text{REASON: } \vec{u} = a\hat{v} + b\hat{w}$$

$$= (a\hat{v}) \cdot (a\hat{v}) + (a\hat{v}) \cdot (b\hat{w}) + \dots$$

$$\dots + (b\hat{w}) \cdot (a\hat{v}) + (b\hat{w}) \cdot (b\hat{w}) \quad \text{REASON: } \underline{\hspace{10cm}}$$

$$= a^2(\hat{v} \cdot \hat{v}) + ab(\hat{v} \cdot \hat{w}) + \dots$$

$$\dots + ba(\hat{w} \cdot \hat{v}) + b^2(\hat{w} \cdot \hat{w}) \quad \text{REASON: } \underline{\hspace{10cm}}$$

$$= a^2(1) + ab(0) + ba(0) + b^2(1) \quad \text{REASON: } \underline{\hspace{10cm}}$$

$$= a^2 + b^2 \quad \checkmark$$

## FORMULAS

- $d = \sqrt{(x_1 - x_0)^2 + (y_1 - y_0)^2 + (z_1 - z_0)^2}$

- $(x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2 = r^2$

- $\vec{p} = \frac{\vec{v} \cdot \vec{w}}{\|\vec{w}\|^2} \vec{w} = \frac{\vec{v} \cdot \vec{w}}{\vec{w} \cdot \vec{w}} \vec{w}$

- $\vec{u} \cdot (\vec{v} \times \vec{w}) = \begin{vmatrix} u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \\ w_1 & w_2 & w_3 \end{vmatrix}$

- $\vec{L}(t) = \overrightarrow{OP} + t \vec{v} = \langle x_0 + at, y_0 + bt, z_0 + ct \rangle$

- $a(x - x_0) + b(y - y_0) + c(z - z_0) = 0$

- $d = \frac{\left\| \overrightarrow{PQ} \times \vec{v} \right\|}{\|\vec{v}\|}$

- $d = \frac{\left| \overrightarrow{PQ} \cdot \vec{n} \right|}{\|\vec{n}\|}$